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Analysis of the spectrum transform for narrow-band signal passing through nonlinear section of a digital radar receiver

Haijiang Wang^{*}, Yangyang Deng, Bao Dong and Debin Su

Abstract

In this paper, with the analytical method, the problem of unexpected bandwidth occupying is investigated firstly when a narrow-band signal passes through the inertialess nonlinear section of a digital radar receiver. Afterwards, the frequency aliasing that is caused by the digitalization is studied. To solve these two issues, the selection of the sampling frequency is of great importance. In this paper, a maximizing minimum arc-distance strategy is proposed, which is dependent on the frequency range of the signal. The arc-distance method is designed for optimizing the sampling frequency. Furthermore, with this method, the minimum arc distances between the frequency bands of the signal and the interferences can be calculated. The inter-band arc distances are important references for optimizing the transition bandwidth of the filter after the sampling and demodulation process.

Keywords: Spectrum transform, Narrow-band signal, Nonlinear section, Digital radar receiver

1 Introduction

The dynamic range of the signal to be processed by some certain kinds of radar receivers is very large. For example, the RF signal's dynamic range of weather radar can be as wide as about 94 to 100 dB [1]. To meet this wide dynamic range requirement, automatic gain control (AGC) in IF stage plays an indispensable role in analog circuitry. With the rapid development and popularization of digital electronic technology, in recent years, to improve performance and simplify system, hardware digitization has long been introduced in this area and more and more analog function circuits have been replaced with digital ones [2, 3]. Orthogonal demodulation now proceeds digitally with satisfactory performance and the function of amplification of IF stage is actually saved [4, 5]. As ADC is moved further towards radar's analog front end by employing advanced under-sampling ADC chip, the signal added to AD converter has a large dynamic range because of the absence of AGC function which is originally in the analog circuit, and nonlinear effects caused by the strong signal become apparent. Especially, after the digitization of the signal which has been subjected to nonlinear distortion,

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Many researchers have investigated the nonlinearity in digital communication and radar systems. For example, Lin et al. analyzed the problem of fifth-order nonlinear distortion and spectral regrowth in a communication system [6, 7]. Wang et al. studied the nonlinearity of the mixer and VCO in the FMCW V-band radar receiver [8]. In [9], Harrington discussed the nonlinearity of the active array radar and gave a spectral analysis of thirdorder intermodulation clutter. In [10], Mark B. Yeary analyzed the intermodulation product caused by the power amplifier's nonlinear response. In [11], A. W. Doerry et al. investigated spurious effects of analog-to-digital conversion nonlinearities on radar range-Doppler maps. And in [12], Grimm et al. focused on the analysis and digital mitigation of nonlinear distortion in softwaredefine radio receivers; they derived a nonlinear distortion model in time and frequency domain and suggested an adaptive digital feed-forward linearization structure to mitigate the nonlinear distortion. But by now, few literatures were seen to take the nonlinear section and digitalization processing as a whole to analyze the spectrum transform of the input signal. Especially, in the



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existing work, the effect of sampling and the selection of sampling frequency were seldom investigated intensively.

Because the nonlinearity section has a suppression effect upon the strong signal, some people have the idea of trying to take advantage of the nonlinearity to realize automatic gain control function. It is considered that the signal frequency bands are duplicated and shifted to the position of each harmonic frequency of the carrier because of the nonlinearity, forming several harmonic frequency bands. So by choosing the sampling frequency carefully, it is expected that the fidelity of signal can be ensured and the effect of AGC can be achieved at the same time through digital filtering. In this paper, however, the research shows that the situation is not good as seems to be.

In fact, the duplication and shifting property of the signal frequency band mentioned above is based on the assumption of "light" modulation. Assume that the relationship between input and output of inertialess and nonlinear section can be expressed as the following equation

$$\mathbf{y}(t) = f(\mathbf{x}(t)). \tag{1}$$

Under the assumption of "light" modulation, the magnitude of the carrier wave of input signal is much greater than that of its modulation signal s(t), that is

$$x(t) = V_m \cos 2\pi f_0 t + s(t), \tag{2}$$

where $V_m > \max[|s(t)|]$. If the dynamic range of s(t) is small enough, the output signal can be expressed as first-order Taylor expansion near the carrier signal:

$$y(t) = f(V_m cos 2\pi f_0 t) + f'(V_m cos 2\pi f_0 t)s(t).$$
(3)

Because f and f' are both periodic functions of t, they can be expanded into Fourier series [13]:

$$f(V_m cos 2\pi f_0 t) = \sum_{n=-\infty}^{\infty} A_n(V_m) e^{j2n\pi f_0 t},$$
(4)

and

$$f'(V_m cos 2\pi f_0 t) = \sum_{n=-\infty}^{\infty} B_n(V_m) e^{j2n\pi f_0 t}.$$
 (5)

where

$$A_n(V_m) = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(V_m \cos\varphi) e^{-jn\varphi} d\varphi, \qquad (6)$$

$$B_n(V_m) = \frac{1}{2\pi} \int_{-\pi}^{\pi} f'(V_m \cos\varphi) e^{-jn\varphi} d\varphi.$$
(7)

Substituting Eqs. (6) and (7) into Eq. (3), and carrying out Fourier transform, we obtain

$$Y(f) = \sum_{n=-\infty}^{\infty} A_n \delta(f - nf_0) + \sum_{n=-\infty}^{\infty} B_n S(f - nf_0).$$
(8)

The first summation item on the right-hand side of the expression above represents the spectrum line of each harmonic wave caused by carrier. While the second summation item represents the duplication and shifting near each harmonic frequency of the modulated signal spectrum. In the above equation,

$$B_0(V_m) = \frac{1}{2\pi} \int_{-\pi}^{\pi} f'(V_m \cos \varphi) d\varphi$$
 is the gain of the signal.

If the gain decreases with the increase of carrier amplitude, it can realize the function of automatic gain control.

This is the theoretical basis of the idea of duplication and shifting. However, for the "deep" modulated signal, especially for the pulse-modulated signal, such assumptions will not hold.

Now we try to discuss the problem in another way. Firstly, the nonlinear function y = f(x) can be expressed as the power series

$$y(t) = a_1 x(t) + a_2 x^2(t) + a_3 x^3(t) + \dots + a_n x^n(t).$$
(9)

We will discuss the property of the output signal's spectrum Y(f) transformed from the output signal y(t) under the condition of knowing the spectrum X(f) transformed from the input signal x(t).

Suppose that the spectrum of x(t) is

$$X(f) = \int_{-\infty}^{\infty} x(t) e^{-j2\pi f t} dt,$$
(10)

then the Laplace transform of the spectrum denoted by a subscript is

$$X_L(s) = \int_{-\infty}^{\infty} X(f) e^{-sf} df.$$
(11)

So the spectrum of the product of x(t) and y(t) can be expressed as

$$Z(f) = \int_{-\infty}^{\infty} x(t)y(t)e^{-j2\pi ft}df = \int_{-\infty}^{\infty} x(t) \left[\int_{-\infty}^{\infty} Y(\xi)e^{j2\pi\xi t}d\xi\right]e^{-j2\pi ft}df$$
$$= \int_{-\infty}^{\infty} Y(\xi) \left[\int_{-\infty}^{\infty} x(t)e^{-j2\pi (f-\xi)t}df\right]d\xi = \int_{-\infty}^{\infty} X(f-\xi)Y(\xi)d\xi.$$
(12)

Its Laplace transform is

$$Z_{L}(s) = \int_{-\infty}^{\infty} Z(f)e^{-sf}df = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} X(\xi)Y(f-\xi)d\xi e^{-sf}df$$
$$= \int_{-\infty}^{\infty} X(\xi) \left[\int_{-\infty}^{\infty} Y(f-\xi)e^{-sf}df \right] d\xi = Y_{L}(s) \int_{-\infty}^{\infty} X(\xi)e^{-s\xi}d\xi$$
$$= X_{L}(s)Y_{L}(s).$$
(13)

That is to say, the Laplace transform of the spectrum of the product of two signals is the product of the Laplace transform of spectrum of these two signals. If we use the symbol $X^{\otimes n}(f)$ to denote the spectrum with *n*th power of a signal, then the Laplace transform of $X^{\otimes n}(f)$ is exactly the *n*th power $X_L^n(s)$ of the Laplace transform of the signal's spectrum. The following equations show the relationship between the symbols above clearly and intensively. That is to say, if

$$x(t) \xrightarrow{\text{Fourier Transform}} X(f) \xrightarrow{\text{Laplace Transform}} X_L(s),$$
 (14)

then

$$x^{n}(t) \xrightarrow{\text{Fourier Transform}} X^{\otimes n}(f) \xrightarrow{\text{Laplace Transform}} X^{n}_{L}(s).$$
 (15)

This result is greatly helpful for us to analyze the spectrum transform of a signal passing through the non-linear section.

2 The spectrum transform of baseband signal passing through nonlinear section

If we only focus on the problems about frequency band occupation caused by nonlinearity and do not care about the details of the spectrum shape, it might as well assume that signal $x_b(t)$ has uniform spectrum within a frequency band

$$X_b(f) = \begin{cases} 1 & |f| \le b \\ 0 & \text{elsewhere} \end{cases} = u(f+b) - u(f-b), \quad (16)$$

where u(f) is the unit step function, and *b* represents the single-side bandwidth. Its Laplace transform is easy to draw:

$$X_{bL}(s) = \frac{e^{sb} - e^{-sb}}{s}.$$
 (17)

The region of convergence is at the right half of *s*-plane: Re(s) > 0. Its *n*th power is

$$X_{bL}^{n}(s) = \frac{\left(e^{sb} - e^{-sb}\right)^{n}}{s^{n}} = s^{-n} \sum_{k=0}^{n} \left(-1\right)^{k} C_{n}^{k} e^{s(n-2k)b}, \quad (18)$$

where $C_n^k = \frac{n!}{k!(n-k)!}$, according to the time-shift theorem, the inverse transform of the above equation is a linear

combination of the several delay items from the inverse transform of s^{-n} . The inverse transform of s^{-n} is

$$u(f)\frac{f^{n-1}}{(n-1)!},$$
(19)

so

$$X_{b}^{\otimes n}(f) = \frac{1}{(n-1)!} \sum_{k=0}^{n} (-1)^{k} C_{n}^{k} u[f + (n-2k)b][f + (n-2k)b]^{n-1}.$$
(20)

Because $y_b(t) = \sum_{n=1}^{N} a_n x_b^n(t)$, so it can be obtained that

$$Y_{bL}(s) = \sum_{n=1}^{N} a_n X_{bL}^n(s),$$
(21)

and

$$Y_{b}(f) = \sum_{n=1}^{N} a_{n} X_{b}^{\otimes n}(f).$$
 (22)

Substituting Eq. (16) into Eq. (22) leads to

$$Y_{b}(f) = \sum_{n=1}^{N} \frac{a_{n}}{(n-1)!} \left\{ \sum_{k=0}^{n} (-1)^{k} C_{n}^{k} u[f + (n-2k)b][f + (n-2k)b]^{n-1} \right\}$$
(23)

Figure 1 shows the normalized spectrum of the items from the first to fifth power of the baseband signal. It can be seen from the figure that the bandwidth of the signal increases by times of corresponding power order. This is because combinatorial frequency items are produced by the multiplication of different frequency components within the signal frequency band. The frequency bands which is produced by two and larger power of the signal includes signal distortion. The spectrum attenuated at the band edge, so magnitude 0.1 is taken to calculate the bandwidth ratio of the first 10 power items to the baseband signal, the result is indicated in Table 1.

Plot the data of Table 1 in Fig. 2, by observation we can find out that bandwidth ratio k is approximately proportional to the square root of the harmonic order, that is

$$k(n) = a\sqrt{n}.\tag{24}$$

According to the criterion of minimum mean square error, the coefficient can be determined as a = 1.2544. For nonuniform signal spectrum, the value of a will be smaller.



3 The spectrum transform of modulated signal passing through nonlinear section

Assume that a modulated signal has the following spectrum

$$X(f) = \begin{cases} 1 & |f+F| \le b \text{ or } |f-F| \le b \\ 0 & \text{elsewhere} \end{cases}$$
$$= X_b(f+F) + X_b(f-F), \tag{25}$$

then its Laplace transform can be figured out as

$$X_L(s) = (e^{sF} + e^{-sF})X_b(s).$$
 (26)

The Laplace transform of the *n*th power item's spectrum is

$$X_{L}^{n}(s) = \left(e^{sF} + e^{-sF}\right)^{n} X_{bL}^{n}(s) = X_{bL}^{n}(s) \sum_{m=0}^{n} C_{n}^{m} e^{s(n-2m)F}.$$
 (27)

Table 1 Bandwidth ratio of the first 10 power items

Power n	Bandwidth ratio <i>k</i>
1	1.
2	1.8
3	2.2254
4	2.5264
5	2.8099
6	3.0716
7	3.3118
8	3.5357
9	3.7464
10	3.9459

From this, the spectrum of the *n*th power item can be deduced:

$$X^{\otimes n}(f) = \sum_{m=0}^{n} C_{n}^{m} X_{b}^{\otimes n} [f + (n-2m)F].$$
 (28)

Spectrum of the first power to the fifth power item is shown in Fig. 3.

From Eq. (28) and Fig. 3, it is not difficult to find out that even power items produce even order harmonic frequency band up to the specific even order, and odd power items produce odd order harmonic frequency band up to the specific odd order. So the fundamental frequency band is contaminated by odd power items, and thereamong the frequency component produced around the fundamental frequency F by the 2k - 1 -th power item is

$$X_{c}^{k}(f) = C_{2k-1}^{k} X_{b}^{\otimes 2k-1}(f - F).$$
⁽²⁹⁾

So the spectrum of y(t) around the fundamental frequency *F* is obtained:

$$Y_{1}(f) = \sum_{k \ge 1} a_{2k-1} C_{2k-1}^{k} X_{b}^{\otimes 2k-1}(f-F) = a_{1} X_{b}^{\otimes 1}(f-F) + 3a_{3} X_{b}^{\otimes 3}(f-F) + 10a_{5} X_{b}^{\otimes 5}(f-F) + \cdots.$$
(30)

Thus, it can be seen that the modulated signal has been contaminated around the carrier frequency by the third and larger odd power items.





4 Filtering of the harmonic aliases after nonlinear transform

From the discussion in Section 3, it can be seen that the contamination put on the signal frequency band by the combinatorial frequency items is inevitable. In fact, the signal has experienced this kind of contamination before sampling. If the degree of contamination is mild, the signal is still usable and can be put into digital processing after sampling. However, the sampling will produce aliasing problem of the harmonic frequency band, and this will bring new challenges to filtering processing.

To show the aliasing effect more intuitively, the spectrum of the signal after digitization can be plotted onto a cylindrical surface which can indicate the periodic property of the digital spectrum and we call it "cylindrical spectrum".

Suppose that the digital spectrum of the signal after sampling is:

$$X(\omega) = \dots + V(\omega + 2\pi) + V(\omega) + V(\omega - 2\pi) + \dots$$
$$= \sum_{k=-\infty}^{\infty} V(\omega + 2k\pi)$$
(31)

where $V(\omega)$ is the scaled analog spectrum. Firstly, let us only consider the first two terms $V(\omega)$ and $V(\omega + 2\pi)$ in Eq. (30). A length of magnitude spectrum $|V(\omega)|$ within the interval $(-\pi, \pi]$ is drawn in solid line in Fig. 4a, meanwhile, the magnitude spectrum $|V(\omega + 2\pi)|$ within the interval $(-\pi, \pi]$ is drawn in dotted line. Suppose that we cut down this strip of paper on which the scaled analog spectrum in the interval $(-\pi, \pi]$ is drawn and stick it on a cylinder whose cross section is a unit circle, then a cylindrical spectrum is obtained, which is shown as Fig. 4b.

Figure 5 shows a signal with a center frequency of 60 MHZ and a bandwidth of 8 MHZ which has passed through a nonlinear section with the first to the fifth power items. The sampling frequency is 48 MHZ, the signal spectrum before sampling is shown in Fig. 5a, and the spectrum after digitization is plotted onto a cylindrical surface which can indicate the periodic property of the digital spectrum, as shown in Fig. 5b. From the figure, it can be found that not only are there frequency components generated by the third and the fifth power in the signal band but also there are frequency components that are originally far from the signal band in the analog spectrum. Among them, the most significant aliases are brought by the nonlinearity components at $5f_0$ and $-3f_0$, whose harmonic band completely covers the signal band. This is because according the equation below, the two digital frequencies corresponding to these two analog frequencies are both equal to 0.5π , which is the digital frequency of the carrier:

$$\omega = \pi \bigg[\mod \bigg(\frac{2f}{f_s} + 1, 2 \bigg) - 1 \bigg]. \tag{32}$$

The relationship between f and ω in Eq. (32) is drawn as Fig. 6. The bold lines denote the signal





frequency range and the harmonic frequency ranges. The shaded areas denote the signal frequency band after sampling. Obviously, the contamination is very serious under this situation, because the signal frequency band is seriously overlapped by the other ones.

In order to eliminate the harmonic aliasing, the sampling frequency must be chosen carefully. For

this, we define a parameter at first: the ratio of the carrier frequency to the sampling frequency, that is

$$x = \frac{f_0}{f_s} = f_0 T_s.$$
(33)

Consider the minimum value of the arc distances between the signal frequency band (the center frequency is



 f_0 and the bandwidth is *B*) and all the harmonic frequency bands generated by the nonlinear items whose center frequencies are not f_0 :

$$D_{cmin}(x) = \min_{f_k \neq f_0} \{ D_{cB}(f_k, B_k, f_0, B, x/f_0) \},$$
(34)

where DcB is the arc distance and is defined as

$$D_{\rm cB} = max(0, \ \left| mod \left[2x(f_k - f_0)/f_0 + 1, \ 2 \right] - 1 \right| - x(B + B_k)/f_0 \right).$$
(35)

A curve of the minimum arc distance $D_{c \min}(x)$ can be drawn by changing the value of x gradually, which is shown in Fig. 7. The solid line represents the minimum arc distance between the signal frequency band and the harmonic frequency bands with center frequencies not equal to the carrier frequency, which are generated by nonlinearity when the first to fifth power are all exist.

It can be noticed that there are several peaks on the curve of $D_{c\min}(x)$. The coordinate position of the peak corresponding to the largest x is x = 0.43, $D_{c\min}(x) = 0.0619$, and the corresponding sample frequency is $f_s = 139.5349MHz$. The $f \leftrightarrow \omega$ graph in this case is shown as Fig. 8, and the cylindrical spectrum diagram is shown as Fig. 10b. Indeed, with the minimum arc distance method, by choosing the sampling frequency carefully, the

harmonic frequency band caused by nonlinearity has been separated from the signal frequency band, so the contamination to the signal frequency band is greatly eliminated.

If a nonlinear section has the odd symmetry property, namely f(-x) = -f(x), then all the even power items at the right side of equation (9) will disappear. In this case, the curve of $D_{c\min}(x)$ is shown as the dotted line in Fig. 7. On this line, the abscissas of the peaks increase greatly compared to the ones on the solid line. The sampling frequency corresponding to the peak with the maximum abscissa is $f_s = 68.1818$ MHz, while the corresponding minimum arc distance is only 0.0336, making the filter design and implementation after sampling and digital demodulation very difficult. In order to get an enough large minimum arc distance, we can choose x = 0.62; $D_{c \min}(x) = 0.1655$, and the corresponding sampling frequency is $f_s = 96.7742$ MHz. In this situation, the $f \leftrightarrow \omega$ relation is shown as Fig. 9, and its cylindrical spectrum diagram is shown as Fig. 10d.

5 Conclusion

Compared to the bandwidth of the baseband, the bandwidth of frequency band generated by the high power items of the baseband signal that has passed through nonlinear section of a digital radar receiver is wider. In theory, the bandwidth generated by nth power item is n





times of the width for the baseband. Although due to the attenuation on band edge, the bandwidth calculated at a certain level increases slow along with *n* (approximately proportional to \sqrt{n}), but it is still much wider than that of the baseband. The signal of modulated narrow band will generate a series of harmonic frequency band after passing through the nonlinear section of a

digital radar receiver. The harmonic frequency bands are shifted copy of the spectrum from respective power item of baseband signal according to the integer multiple of the carrier frequency, rather than the simple duplicated and shifted copy of the signal spectrum of the baseband signal. Each item of odd order power generates frequency component near the fundamental frequency,





causing the unnecessary contaminant to the fundamental frequency. So, it is impossible to eliminate the contaminant by using the filtering method.

If the contaminant discussed above is minor, it is still acceptable to sample the signal and make the digital processing. However, the sampling frequency is suggested to be selected prudently. In this paper, a maxmin arcdistance strategy that is dependent on the frequency range of the signal is proposed. The arc-distance method is designed for optimizing the sampling frequency. Furthermore, with this method, the minimum arc distances between the frequency bands of the signal and the interferences can be calculated. The inter-band arc distances are important references for optimizing the transition bandwidth of the filter after the sampling and demodulation process.

Competing interests

The authors declare that they have no competing interests.

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