

ERRATUM

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# Erratum to: A novel algorithm of low sampling rate GPS trajectories on map-matching

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## 1 Erratum

Since the publication of our article [1] we have become aware that we omitted to cite the work of Lou et al. (2009) [2]. The first sentence of subsection 3.3 should read as follows: “In subsections 3.3 and 3.4, “Time Analysis” and “Result Matching”, which are based on the methods proposed by Lou et al. (2009) [2], are utilized as the part of our design flow. These two steps are summarized as follows.” In addition, the legend for Fig. 3 should read: “Influence factors of track point matching time speed information. Adapted from Lou et al. (2009) [2] with permission.” We apologize to Lou et al. and to readers for this omission.

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## References

1. Y. Liu, Z. Li a novel algorithm of low sampling rate GPS trajectories on map-matching. *EURASIP J. Wirel. Commun. Netw.* **2017**, 30 (2017). doi: 10.1186/s13638-017-0814-6
2. Y. Lou, C. Zhang, Y. Zheng, X. Xie, W. Wang, Y. Huang, in *Proceedings of the 17th ACM SIGSPATIAL International Conference on Advances in Geographic Information Systems* (pp. 352–361), ACM. Map-matching for low-sampling-rate GPS trajectories (2009)

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